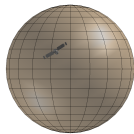
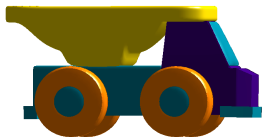
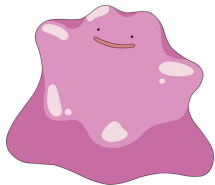


# About interpolation on manifolds...

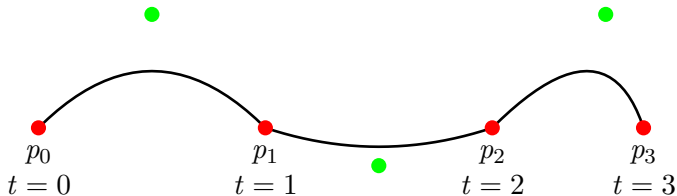


# How to interpolate points on curved spaces ?

Light fast general good looking interpolation

# How to interpolate?

Each segment between two consecutive points is a Bézier function.



**Light**

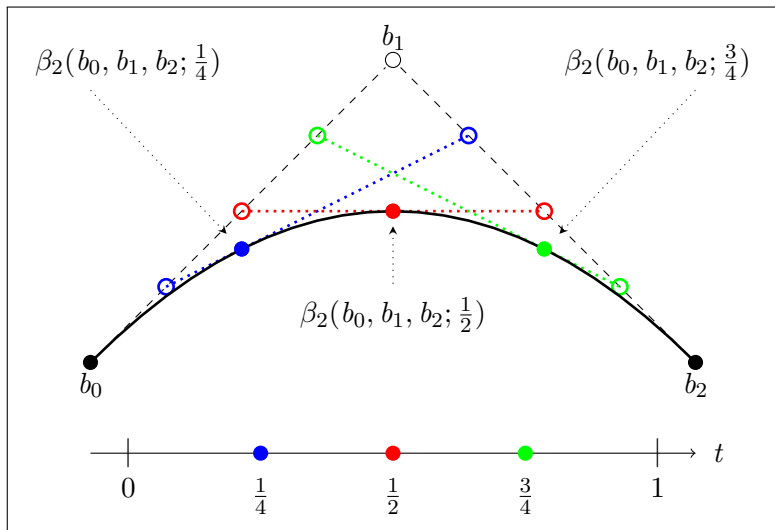
fast

general

good looking

**interpolation**

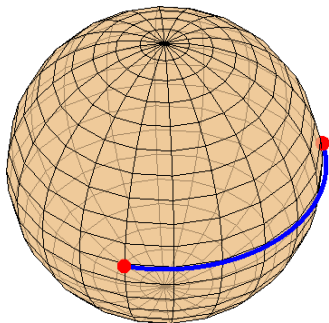
# Reconstruction : the De Casteljau algorithm



**Light**   **fast**   general   good looking   **interpolation**

# How to generalize Bézier curves to manifolds?

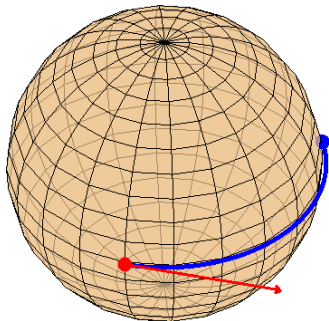
The straight line is a geodesic



# How to generalize Bézier curves to manifolds?

The exponential map to construct the geodesic

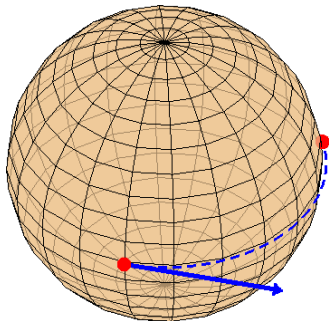
$$\gamma(t) = \text{Exp}_x(t\xi_x)$$



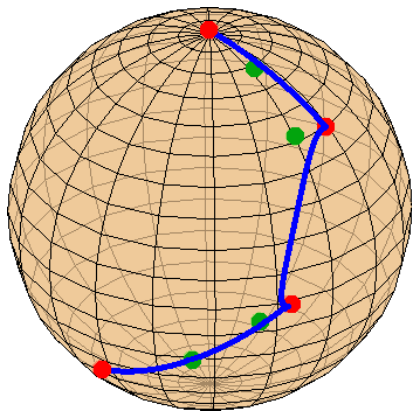
# How to generalize Bézier curves to manifolds?

The logarithmic map to determine the starting velocity

$$\text{Log}_x(y) = \xi_x$$



# Piecewise interpolation on the sphere



Light

fast

general

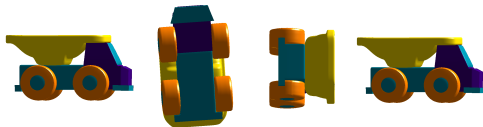
good looking

interpolation



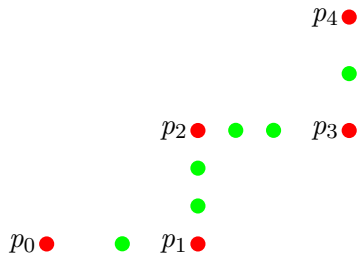
# Interpolation on Riemannian manifolds with a $C^1$ piecewise-Bézier path

Pierre-Yves Gousenbourger



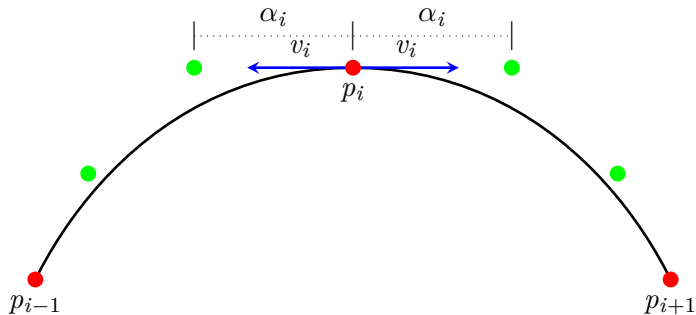
8 october 2014

# Good-looking curve on the Euclidean space



Find the optimal position of control points

# $\mathcal{C}^1$ -piecewise Bézier interpolation



$$b_i^L = \text{Exp}_{p_i}(-\alpha_i v_i)$$

$$b_i^R = \text{Exp}_{p_i}(\alpha_i v_i)$$

# Optimal $\mathcal{C}^1$ -piecewise Bézier interpolation

Minimization of the mean square acceleration of the path

$$\underbrace{\min_{\alpha_i} \int_0^1 \|\ddot{\beta}_2^0(\alpha_i; t)\|^2 dt + \sum_{i=1}^{n-1} \int_0^1 \|\ddot{\beta}_3^i(\alpha_i; t)\|^2 dt + \int_0^1 \|\ddot{\beta}_2^n(\alpha_i; t)\|^2 dt}_{\text{Second order polynomial } P(\alpha_i)}$$

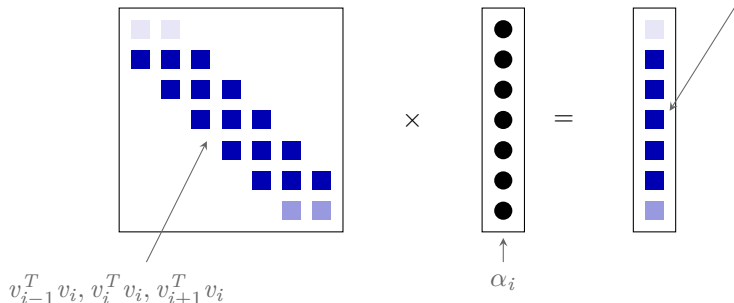
$$\nabla P(\alpha_i) !$$

# Optimal $\mathcal{C}^1$ -piecewise Bézier interpolation

Minimization of the mean square acceleration of the path

$$\min_{\alpha_i} \underbrace{\int_0^1 \|\ddot{\beta}_2^0(\alpha_i; t)\|^2 dt + \sum_{i=1}^{n-1} \int_0^1 \|\ddot{\beta}_3^i(\alpha_i; t)\|^2 dt + \int_0^1 \|\ddot{\beta}_2^n(\alpha_i; t)\|^2 dt}_{\text{Second order polynomial } P(\alpha_i)}$$

$$\sim (p_{i-1} - p_i)^T v_i$$

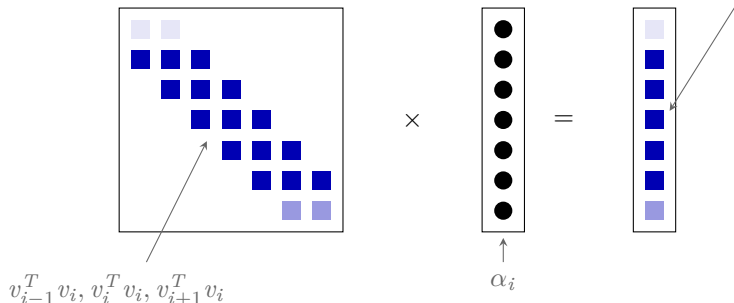


# Optimal $\mathcal{C}^1$ -piecewise Bézier interpolation

Minimization of the mean square acceleration of the path

$$\min_{\alpha_i} \underbrace{\int_0^1 \|\ddot{\beta}_2^0(\alpha_i; t)\|^2 dt + \sum_{i=1}^{n-1} \int_0^1 \|\ddot{\beta}_3^i(\alpha_i; t)\|^2 dt + \int_0^1 \|\ddot{\beta}_2^n(\alpha_i; t)\|^2 dt}_{\text{Second order polynomial } P(\alpha_i)}$$

$$\sim (p_{i-1} - p_i)^T v_i$$



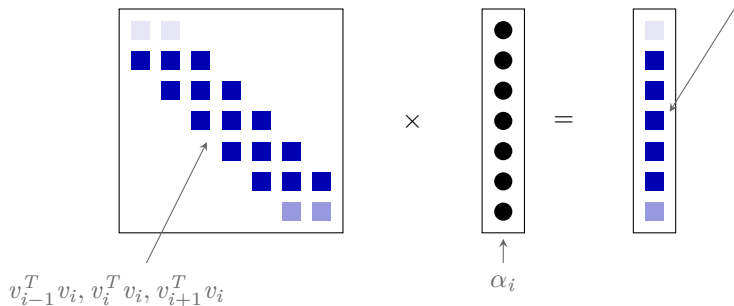
# Optimal $\mathcal{C}^1$ -piecewise Bézier interpolation

Minimization of the mean square acceleration of the path

$$\min_{\alpha_i} \int_0^1 \|\ddot{\beta}_2^0(\alpha_i; t)\|^2 dt + \underbrace{\sum_{i=1}^{n-1} \int_0^1 \|\ddot{\beta}_3^i(\alpha_i; t)\|^2 dt + \int_0^1 \|\ddot{\beta}_2^n(\alpha_i; t)\|^2 dt}_{\text{Second order polynomial } P(\alpha_i)}$$

Second order polynomial  $P(\alpha_i)$

$$\sim (\text{Log}_{p_i}(p_{i-1}))^T v_i$$



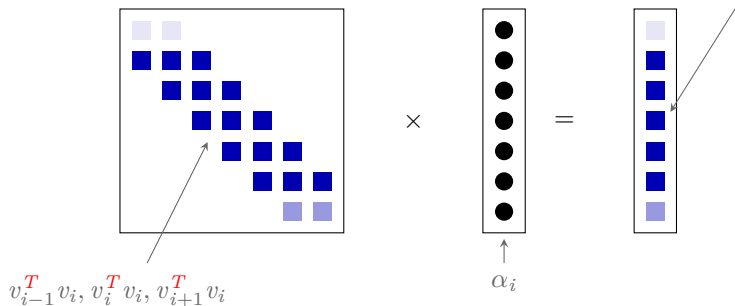
# Optimal $\mathcal{C}^1$ -piecewise Bézier interpolation

Minimization of the mean square acceleration of the path

$$\min_{\alpha_i} \int_0^1 \|\ddot{\beta}_2^0(\alpha_i; t)\|^2 dt + \underbrace{\sum_{i=1}^{n-1} \int_0^1 \|\ddot{\beta}_3^i(\alpha_i; t)\|^2 dt + \int_0^1 \|\ddot{\beta}_2^n(\alpha_i; t)\|^2 dt}_{\text{Second order polynomial } P(\alpha_i)}$$

Second order polynomial  $P(\alpha_i)$

$$\sim (\text{Log}_{p_i}(p_{i-1}))^T v_i$$



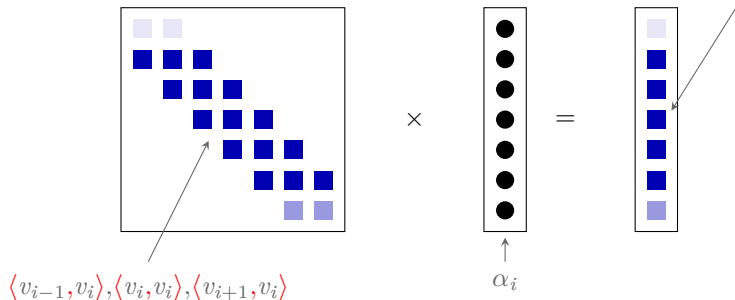


# Optimal $\mathcal{C}^1$ -piecewise Bézier interpolation

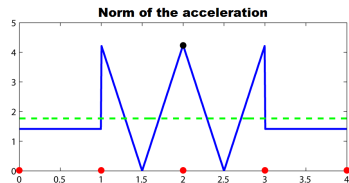
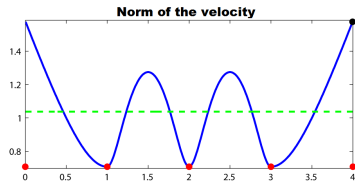
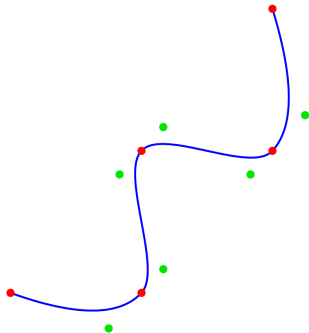
Minimization of the mean square acceleration of the path

$$\min_{\alpha_i} \int_0^1 \|\ddot{\beta}_2^0(\alpha_i; t)\|^2 dt + \underbrace{\sum_{i=1}^{n-1} \int_0^1 \|\ddot{\beta}_3^i(\alpha_i; t)\|^2 dt + \int_0^1 \|\ddot{\beta}_2^n(\alpha_i; t)\|^2 dt}_{\text{Second order polynomial } P(\alpha_i)}$$

$$\sim \langle \text{Log}_{p_i}(p_{i-1}), v_i \rangle$$

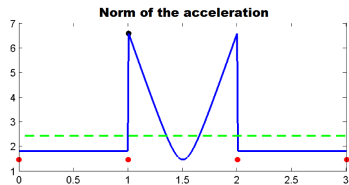
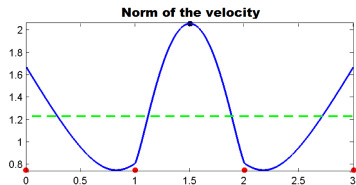
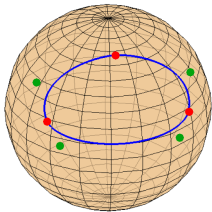


# A result on $\mathbb{R}^2$

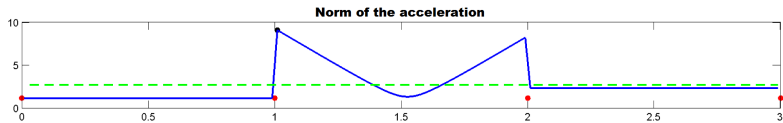
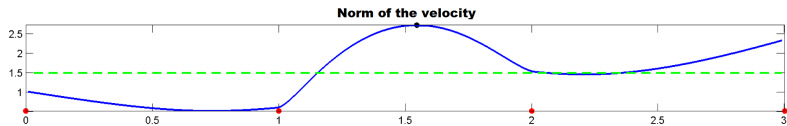


Light fast general good looking interpolation

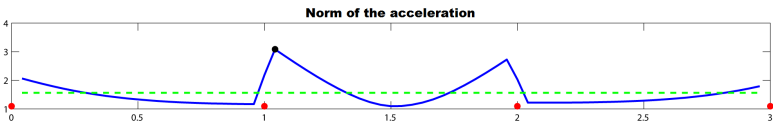
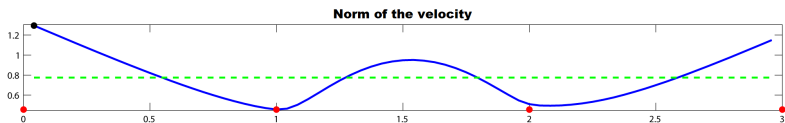
# Generalization to manifolds : the sphere $\mathbb{S}^2$



# Generalization to manifolds : the special orthogonal group $SO(3)$



# Generalization to manifolds : morphing of shapes



# Conclusions

**Light fast general good looking interpolation**

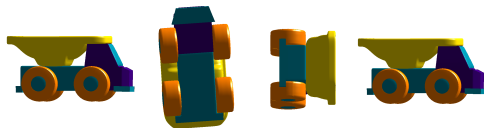
No choice of velocities  $v_i$ ? (Arnould, Samir, Absil)

Application to manifolds of high dimension?

Any questions ?

# Interpolation on Riemannian manifolds with a $\mathcal{C}^1$ piecewise-Bézier path

Pierre-Yves Gousenbourger



8 october 2014